



PROJETO DE AERONAVES AIRCRAFT DESIGN – 10403

2018/2019



FAST CARGO UAV

UAV-18

Project Description

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1. INTRODUCTION

The international aerospace sector has increasingly used in recent years unmanned aerial vehicles (UAV - Unmanned Aerial Vehicle) for missions of various types, such as: aerial photography, military reconnaissance, atmospheric research at high altitude, radio communication, surveillance, fire detection, technology development, etc.. Despite the technology involved, UAVs have dimensions smaller than manned aircraft, making their operation more flexible and more economical. The increasing automation and communication capabilities and the evolution of available materials has allowed the operation of these aircraft at distances and altitudes greater than ever, increasing their potential by making them equal, or even superior, to other aircraft that need to carry on board systems for crew support. For short distance surveillance applications, the investment required for the development and operation of a UAV is comparatively lower than equivalent manned aircraft so that its use in these tasks results in a cost-benefit ratio much more attractive. The UAV sector is the only sector of the aerospace industry with significant growth in the last 30 years, with an average growth rate of over 14% per year.

The UAV sector is rapidly flourishing and in many cases it is a source of concepts and technologies for manned aircraft. Currently, most UAVs in operation have military applications. The use of UAVs in civil applications is, however, growing rapidly with the appearance of new concepts of operation and the creation and maturation of appropriate legislation. Portugal needs to stay in this important aerospace area in order to be more autonomous in the development of technological means essential to the sustainability of its resources and its regional and national economic maturity, to employ its qualified manpower and to be a competitive exporter of technology.

Portugal also needs the use of UAVs in various areas of activity. Monitoring of forest areas which in recent years have succumbed to fires is an important example. The application of surveillance unmanned aerial vehicles allows a high degree of uptime and availability in the tasks of this nature and is a complementary means of ground surveillance and satellite monitoring already in use. The application of new UAV concepts to new civil scenarios that can be economic viable is also important.

In the past few years electric propulsion for aircraft has seen tremendous developments and a widespread use. Its application ranges from the model aircraft, UAVs, sailplanes and ultralight aircraft. Because batteries have a limited energy density, resulting in flights of short duration, the use of fuel cells for battery charging is an interesting option that has already been exploited. Conventional propulsion with a piston engine allows flights with longer duration and with the help of an alternator coupled to the engine batteries, that provide on-board power for systems, can be recharged in flight. To avoid consumption of gasoline to produce electricity, the incorporation of photovoltaic cells on the aircraft can provide part or all of the electrical energy required on board. In some situations a hybrid propulsion system may be preferred.

The main objective of this subject is to show students what the conceptual design of an aircraft is and what steps are necessary to follow given mission and performance requirements, design constraints, design methods and the need for optimization. To achieve this, the knowledge gained will be applied to the design of a new aircraft subjected to specific requirements. The optimization of the project is of extreme importance in the development of a new aircraft.

This project description presents the requirements that the aircraft must respond to in terms of mission, configuration, performance, systems, materials and design standards. It also

describes the necessary tasks to be performed during the semester and the work plan to follow. This project requires dedication and continuous work to ensure that deadlines are met and results lead to a good design.

2. REQUIREMENTS

The current requirements present a need for an autonomous UAV (also capable of being remotely piloted) with the capability to fly efficiently over a relatively long distance to deliver high priority cargo over a network of regional airfields. The requirements for this aircraft are listed below and during the course of the project they must be respected. Possible changes in the requirements will be discussed and agreed upon by the teacher and all the elements involved in the project.

It is required to perform the conceptual and preliminary design of a UAV taking into account some specific design requirements. The aircraft must have good flying qualities to allow easy and precise flying. The vehicle's structure and aerodynamics must be carefully designed to achieve low power consumption levels. Simplicity, robustness and ease of repair are essential to maintain high levels of operational readiness of the UAV.

2.1. Mission

The UAV must be designed for the following mission: it must take-off from an airfield, then climb to a cruise altitude of no less than 1000 m, cruise for at least 200 km to the destination airfield, descend and land. The objective of the operation is to deliver high priority cargo to a single airfield or a series of airfields within a regional area of 1000 km in diameter in a timely and efficient manner. The cargo covered in this need comprises medicines, food, or luxury products, in general fragile and requiring special handling, with a mass varying from 50 kg to 100 kg. The turnaround time should be as low as possible yet less than 30 minutes to allow for urgent cargo dispatching.

It is desirable, though not mandatory, to have a vehicle that can complete the journey through as many airfields as possible in the area given above during the daylight period in a Winter day in Central Europe (around 8 hours). There may be a centrally placed airfield from which the vehicle operates and to which it returns at the end of the journey.

2.2. Performance

The vehicle must show the following performance figures (ISA conditions):

Take-off
Cruise speed
Maximum speed
Flight operational radius
Data link range
Service ceiling
Landing

from an airfield (less than 500 m) above 150 km/h at least 200 km/h at least 200 km at least 200 km (or satellite) at least 1000 m on an airfield (less than 500 m)

2.3. Propulsion

Electric motors and/or piston engines may be selected for this UAV. The possibility of integrating a hybrid propulsion system should be considered for improved flexibility and

increased range. The propellers must be selected to match the motor/engine performance and according to the UAV performance required. The aircraft can either have tractor or pusher propellers and can have as many propulsion units as required. In selecting the motor/engine, careful attention must be given to its durability and reliability. Proper cooling of the motor/engine must be provided. Tilting of the motors/engines may be considered (or not) to fulfil specific operational needs.

2.4. Wings

The wings must be well designed, both aerodynamically and structurally, so that the overall efficiency of the vehicle is high and to allow the required mission to be accomplished with low energy requirements. According to the mission, the wings must be designed for high lift-to-drag ratio. The structure should use high specific strength and high specific stiffness materials to allow for an empty weight as low as possible. A tilting wing may be considered in conjunction with the tilting motors/engines when applicable.

2.5. Fuselage

The fuselage should be slender and light, yet possessing the necessary internal space for systems and payload. It should have high tolerance on payload weight and position. Equipment substitution and payload access should be quick and simple to perform. The payload compartment should be capable of carrying a container which holds the cargo in a proper manner. The payload compartment should have the reference dimensions $800 \text{ mm} \times 500 \text{ mm} \times 700 \text{ mm}$ (length \times width \times height) and should be accessed very quickly to load and unload the cargo container.

2.6. Tail

The tail, when present, must be small and effective. It should use in their structure the same materials selected for the wings.

2.7. Landing Gear

The choice of using a landing gear will depend on the concept of operation proposed. If it exists, it must be rugged, yet simple.

2.8. Payload

The payload (up to 100 kg) must be well secured in the fuselage to avoid any movement during flight. The payload can be considered as a container holding the high priority cargo. For some types of cargo, such as medicines or food, the container must be climate controlled in terms of temperature and humidity. Appropriate electrical power must be provided to the container in these cases.

2.9. Weight and Balance

The centre of gravity (CG) travel must be such that no negative impact on the stability or on the normal operation of the UAV is imposed for any payload weight transported on board. It is important that the maximum take-off mass of the UAV is kept as low as possible

not exceeding 450 kg. The vehicle should be capable to fly without any payload.

2.10. Controls and Systems

The control system will include autopilot boards (or at least physical space for those) which are not required to be selected. Control surfaces, tilting surfaces and motor/engine's tilting mechanisms if applicable must be sized and must be actuated by servo mechanisms. All electronic and electric components and mission equipment must be placed within the fuselage according to their function and in such a way as to allow its quick preparation or replacement. The electric system should be powered by batteries which can be charged by an alternator driven by the engine in a conventional or hybrid propulsion configuration.

2.11. Design Airworthiness Requirements

The design airworthiness requirements that should be used in the structural sizing are the EASA CS-VLA, CS-LSA or CS-23. The design manoeuvre limit load factors are, in principle, +3 and -3, but those should be checked with a V-n diagram. All work performed in the design should aim at achieving high levels of safety and performance.

3. TASKS

There are several tasks in the design project that must be carried out according to the time plan below. All tasks depend on each other so that there must be a close interaction and updating between them. The design process is also iterative in nature but perfection is not possible nor is necessary but an effort must be put forward to achieve a good optimization level in the outcome.

The necessary calculations may be performed with the help of spread sheets and also other analysis computer programs. All drawings should be, preferably, done in CATIA V5.

3.1. Concept of Operations

The exact mission profile and the way it is going to be operationally implemented must be defined and explained. The design of the vehicle will follow from the concept of operations (CONOPS) proposed to respond to the mission requirements.

3.2. Layout

The layout and functionalities of the vehicle must be selected so that the requirements are fully met. This task is very important because it integrates all needs of the other parts of the project into a viable configuration. A preliminary three dimensional (3D) study of all major components must be performed and these must be incorporated in the aircraft structure. 3D drawings must be produced in a CAD system for the complete UAV.

3.3. Aerodynamics and Stability

The aerodynamic study must cover the selection of the aerofoils, geometry and size of the lifting surfaces, nacelles and the computation of the aerodynamic characteristics of the whole vehicle $(C_L, C_D \in C_M)$. It must be assured that all choices made in the overall design do

not impair the aerodynamic performance. A study of the stability and control of the UAV must also be performed.

The aerodynamic work must concentrate on the wings design and tail sizing. These must be optimized having in mind the necessary compromises for different flight conditions.

3.4. Propulsion and Performance

The propulsive system (motor, propeller, power source, fuel system) must be selected and sized according to the requirements. An estimate of the vehicle's performance (speeds, times, battery and/or fuel usage, etc.) must be carried out.

3.5. Systems

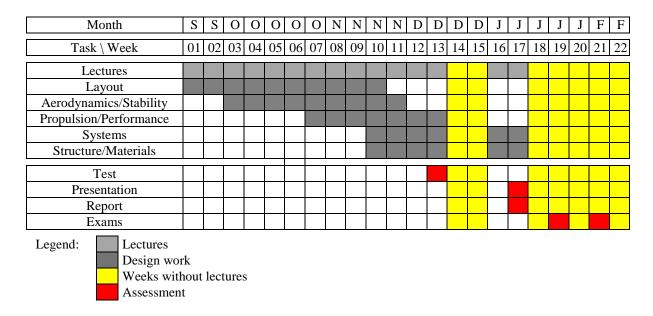
A study of the landing gear system (if it exists), of the control system and of the electric system must be performed. These studies should include not only the selection of the main components and definition of its functionalities but also the positioning of components and routing of cables inside the aircraft. Commercially available components are preferred to speed up both design and building processes. A database containing such data as suppliers, working characteristics, weight, power consumption and price of all components selected must be produced.

3.6. Structure and Materials

The type of structure and materials for the different components of the vehicle must be selected and defined adequately keeping in mind their configuration and function. Preliminary sizing of the wing must be performed. A database containing such data as suppliers, physical characteristics, mechanical characteristics and price of all materials selected must be produced. A study on the manufacturing processes to be used must be carried out together with estimates of weight and balance and total cost of the UAV.

3.7. Time plan

The table below presents the time plan with the tasks required to complete de project.



3.8. Work Requirements

The design is carried out by groups of 5 students. In order for the project objectives to be fulfilled in time all students should work hard.

	Student's Name	N°	Team	E-mail	Task
01	Daniel Carvalhais	33876	A		layout
02	José Gonçalves	33754	A		aerodynamics/stability
03	Luís Santos	33723	A		propulsion/performance
04	António Figueiredo	34325	A		systems
05	José D. Gonçalves	32607	A	jd_goncalves@hotmail.com	structures/materials
06	Marco Martins	35849	В		layout
07	Bárbara Martins	34249	В	martins_barbara@hotmail.com	aerodynamics/stability
08	Filipe Ribeiro	34289	В		propulsion/performance
09	Emanuel Castanho	33804	В		systems
10	Pedro Nunes	33631	В		structures/materials
11	Jorge Panagopoulos	33786	C		layout
12	Rui Pereira	33649	C		aerodynamics/stability
13	Pedro Oliveira	33635	C	p.m.penfiel@hotmail.com	propulsion/performance
14	João Lopes	33564	C		systems
15	José Rocha	33929	C		structures/materials
16	Pedro Dente	34148	D	pedro.dente@hotmail.com	layout
17	Inês Morão	34128	D	ines.morao.96@gmail.com	aerodynamics/stability
18	Flávio Rosa	34013	D	flavio.rosa666@gmail.com	propulsion/performance
19	Alexandra Monteiro	35580	D	alexandra_monteir@hotmail.com	systems
20	Gustavo Ribeiro	33757	D	gustavo-13@live.com.pt	structures/materials
21	Hugo Rocha	34359	Е	hugo_dhs@hotmail.com	layout
22	//	//	Е	//	aerodynamics/stability
23	Miguel Duarte	33520	Е	miguelfixw96@hotmail.com	propulsion/performance
24	Diana Rodrigues	33541	Е	dianacarvalho@gmail.com	systems
25	Leidinir Tavares	34740	Е	leidinir@outlook.pt	structures/materials
26	Harsh Hansraj	35433	F		layout
27	Hugo Pontes	35444	F		aerodynamics/stability
28	Diogo Abranches	35033	F		propulsion/performance
29	Eduardo Godinho	33879	F		systems
30	Nicole Dias	35340	F	nicole13_96dias@hotmail.com	structures/materials
31			G		layout
32	Emanuel Camacho	33878	G		aerodynamics/stability
33	Simão Henriques	33612	G		propulsion/performance
34	José Cruz	28897	G		systems
35	Ana Lourenço	33885	G	a33885@ubi.pt	structures/materials
36	Filipe Monte	33716	Н	filipemonte139@gmail.com	layout
37	Filipa Leal	33683	Н	filipaleal02@gmail.com	aerodynamics/stability
38	Sílvia Silva	33594	Н	silvia_silva12@hotmail.com	propulsion/performance
39	Elisa Duarte	34595	Н	elisaduarte@gmail.com	systems
40	Francisco Carvalho	33801	Н	kiko26373@ivloud.com	structures/materials
41	Brian Silva		I		layout
42	Édi Monteiro		I		aerodynamics/stability
43	Sisenando Fontes		I		propulsion/performance
44	João Mamede		I		systems
45	Laura Martins		I		structures/materials

4. ASSESSMENT

The grade of this subject is given based on one written test (T), one oral presentation (P) and one report (R).

4.1. Test

The test covers all the topics discussed during classes up to the date of the test (17 December 2018 – week 13). The test is divided into two parts: the first is closed book and the second is open book.

4.2. Presentation

Near the end of the semester there will be an oral presentation of the project (7 January 2019 – week 16). In the presentation, when the project is almost complete, each design team (all elements of the team must participate in the presentation) must show to the other teams that their design meets all requirements and explain the steps that led to the final concept. This presentation should take 20-30 minutes for each team, depending on the number of teams that exist.

4.3. Report

Each team must write up a design report that should contain all relevant steps taken in the UAV design process, including layout, decisions made, major calculations, results, etc.. Sketches necessary to fully understand the design and a three view drawing with all major dimensions and aircraft characteristics should also be included. The number of pages is limited to around 30, using letter size 12 and single line spacing. The report should be handed in *pdf* format at the last day of lectures together with the original CAD drawings (11 January 2019 – week 17).

4.4. Exam

There will be no written exam. If students fail the "Frequência" assessment or wish to improve their final grade, they must hand in an improved report of their design project at the dates of the exam, in weeks 19 or 21.

4.5. Grade

The mark of this subject is given by F = 0.3T + 0.2A + 0.5R and approval is obtained if $F \ge 10$. The same is true for the exam final mark.

	Frequência (F = $0.3T + 0.2A + 0.5R$)		100
T	Test	17-12-2018 (09h30)	30
A	Presentation	07-01-2019 (09h00)	20
R	Report	11-01-2019 (24h00)	50
	-		
	Exam $(E = 0.3T + 0.2A + 0.5 R1)$		100
R1	Report (normal period)	??-01-2019 (09h30)	50
R1	Report (recourse period)	??-02-2019 (09h30)	50
	R R1	T Test A Presentation R Report Exam (E = 0.3T + 0.2A +0.5 R1) R1 Report (normal period)	$ \begin{array}{cccccccccccccccccccccccccccccccccccc$

4. Exam (E = 0.3T + 0.2A +0.5 R2) 100 R2 Report (special period) ??-07-2019 (??h00) 50

5. REFERENCES

The books listed below can be used for the design. The design reports of previous years may also be useful as general guideline and source of ideas. However, one must bear in mind that the information contained in them may be incorrect. A lot of information can also be found in the internet using appropriate search criteria.

5.1. Text Book

01. Raymer, D. P., *Aircraft Design: A Conceptual Approach* - 4rd edition, AIAA Education Series, 2006

5.2. Aircraft Design Books

- 02. Gundlach, J., *Designing Unmanned Aircraft Systems: A Comprehensive Approach*, AIAA Education Series, 2012
- 03. Stinton, D., The Design of the Aeroplane, Blackwell Science, 1983
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- 09. Jenkinson, L. R., Simpkin, P., Rhodes, D., Civil Jet Aircraft Design, Arnold, 1999
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- 11. Roskam, J., Airplane Design Volumes I to VIII, The University of Kansas, 1990
- 12. Torenbeek E., Synthesis of Subsonic Airplane Design, Delft University Press, 1982

5.3. Other Books

- 13. Abbot & Doenhoff, Theory of Wing Sections, Dover Publications Inc, 1959
- 14. Barnaby Wainfan, Airfoil Selection Understanding and Choosing Airfoils for Light Aircraft, 1988
- 15. Barnes W. McCormick, *Aerodynamics, Aeronautics and Flight Mechanics* 2nd edition, John Wiley & Sons Inc, 1995
- 16. Bernard Etkin, Lloyd Duff Reid, *Dynamics of Flight, Stability and Control* 3rd edition, John Wiley & Sons Inc., 1996
- 17. Bill Clarke, *The Cessna 172* 2nd edition, Tab Books, 1993
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- 24. JAR-23, Joint Aviation Requirements for Normal, Utility, Aerobatic and Commuter Category Aeroplanes, JAA, 1994
- 25. JAR-27, Joint Aviation Requirements for Small Rotorcraft, JAA, 1993
- 26. JAR-VLA, Joint Aviation Requirements for Very Light Aeroplanes, JAA, 1990
- 27. Ladislao Pazmany, *Landing Gear Design for Light Aircraft* Volumes I & II, Pazmany Aircraft Corporation, 1986
- 28. John Cutler, Understanding Aircraft Structures, Blackwell Science, 1999
- 29. Martín Cuesta Alvarez, Vuelo con Motor Alternativo, Paraninfo, 1981
- 30. Robert C. Nelson, Flight Stability and Automatic Control, McGraw-Hill, 1989
- 31. S. Hoerner, Fluid-Dynamic Drag, Hoerner Fluid Dynamics, 1965
- 32. S. Hoerner, Fluid-Dynamic Lift, Hoerner Fluid Dynamics, 2nd Edition, 1985
- 33. Stelio Frati, L'Aliante, Editore Ulrico Hoepli, Milano, 1946
- 34. Ted L. Lomax, Structural Loads Analysis for Commercial Transport Aircraft Theory and Practice, AIAA Education Series, 1996
- 35. The Metals Black Book Volume 1 Ferrous Metals, Casti Publishing Inc, 1995
- 36. The Metals Red Book Volume 2 Nonferrous Metals, Casti Publishing Inc, 1995
- 37. T. H. G. Megson, *Aircraft Structures for Engineering Students* 2nd edition, Edward Arnold, 1990
- 38. Tony Bingelis, Firewall Forward Engine Installation Methods, EAA Aviation Foundation, 1992
- 39. Tony Bingelis, Sportplane Construction Techniques A Builder's Handbook, EAA Aviation Foundation, 1992
- 40. Tony Bingelis, *The Sportplane Builder Aircraft Construction Methods*, EAA Aviation Foundation, 1992

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